

User manual

Felix 2.0, 3d printer

Version 3 – 17-Septembre-2013



Copyright Information

This document contains proprietary information that is protected by copyright. No part of this document may be photocopied, reproduced, or translated to another language without the prior written consent of FELIXrobotics.

FELIXrobotics BV

Wapendragervlinder 17 3544DL Utrecht Netherlands

Copyright $\ensuremath{\mathbb C}$ 2013 FELIX robotics.



CONTENT

1	Co	Content								
2	Int	roduction3								
3	Sp	Specifications								
4	Pro	e-Flight checks								
	4.1	Calibration of table5								
	4.2	Software installation								
	4.3	Printer software – Repetier-Host								
	4.4	Calibrate the Z-direction/ Connect to printer								
5	lt'	s time for printing!								
6	FA	.Q								
7	Ma	aintenance/Optimal operational tips								
	7.1	General tips for optimal operation18								
	7.2	Cleaning								
	7.3	Regular maintainance								
	7.4	Precautions								
8	Troubleshooting19									
9	Sa	fety 21								
10	o Appendix: Electronical schematics									
11	1 Appendix: Material Data Safety Sheet									
	11.1	PLA								
	11.2	ABS								
12	Ap	pendix: Firmware installation								
13	Ap	pendix: Symbol- and indicatorlights explanation								
14	Appendix: Terms Of Service									



2 INTRODUCTION

First of all thank you choosing FELIXprinters! To get your Felix printer up and running as fast and painless as possible please follow this manual carefully. Don't compare this product with a television, where a user manual is normally not required to get it working properly.

Please **follow instructions carefully** and take your time to get familiar with the product. Please don't make any shortcuts unless you know what you're doing. It's better to spend a few minutes extra on reading, than to wait a week for new parts.

When things are unclear or if you have any remarks or tips, please contact us at support@FELIXprinters.com. We also recommend looking on our forum and get yourself a forum account. You will benefit from the ability to get downloadable and printable upgrades for your printer. Also it is a great source to obtain more knowledge about your printer and printing in general.



3 SPECIFICATIONS

Printing			Electrical	
Print Technology	Fused Filame	nt Fabrication	AC input:	100-240V, 50-60 Hz
Build Volume	25.5 x 20.5 x 2	23.5 cm	Power Requirements	12V DC, 15 Amps
Print Quality	Extreme High Medium Low	50 microns 100 microns 250 microns 320 microns	Connectivity	USB
Postioning Precision	Z: 0.4 microns			
Filament Diameter 1.75 mm		Mechanical		
Nozzle Diameter	0.35 mm		Chassis	Aluminum profiles
			Build platform	Aluminum plate
Software			XY Bearings	Linear ball bearings
Software Bundle:	RepetierHost Skeinforge/SI		Z bearing	Linear ball bearings
File Types:	.STL		Stepper Motors	1.8 deg angle 1/16 micro-stepping
Supports:	Windows, XP and newer			
	Linux (Ubuntu 12.04+)			
	Mac OS X [10.6/10.7/10.8]			
Physical Dimensions				
Weight	7.5kg			
Shipping Weight				
Shipping Box 50x30x30 cm, DIY kit 50x50x60 cm, Assembled unit				
Temperature				
Ambient operating 15-32 °C [60 – 90 °F] temperature		90 °F]		
Storage temperature	0 – 32 °C			
Warmup time				
Heated bed (60 degC)	3 min			
Nozzle (200degC)	1 min			

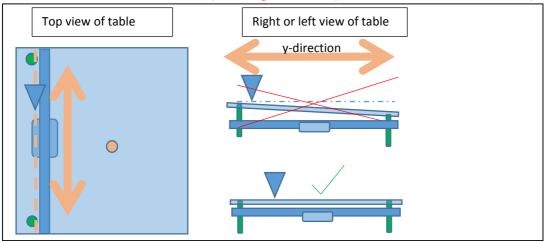


4 PRE-FLIGHT CHECKS

4.1 CALIBRATION OF TABLE

For a successful print it is important that the table is properly calibrated. The distance between the nozzle and table should be the same at every x,y position. The table can be leveled by turning the 3 M4 nuts underneath the heated bed. For the assembled units the calibration should be good, but due to shipment it could be that the calibration is slightly off.

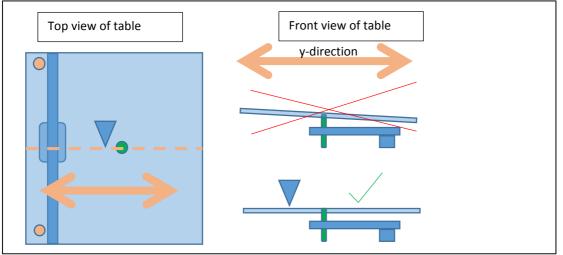
". The calibration should be done by moving the axes by hand, not via interface of computer.



Step 1:

Calibrate the table in y-direction.

- 1. Move the X-axis carriage(extruder) to the homing sensor
- 2. Move the Y-axis (heated bed) to the homing sensor
- 3. Move the table up until approximately 1mm from the hot-end.
- 4. Goal is to move the y-axis and to get the distance between the tip of hot-end and the heated bed the same over the whole movement.
- 5. Move the bed over the whole movement range and while moving adjust the 2 adjustment nuts underneath the plastic parts under the table along the rail to level out the table in y-direction.
- 6. Move the table a little closer to the hot-end and repeat the previous step until the distance is the same over the whole length.



Step 2:

Calibration in x-direction

- 7. Move the table to the middle of its movement range
- 8. Move the X-axis carriage over its movement range. While moving check the distance between the hot-end and bed. If the distance is not even, adjust it with the nut which supports the middle of the table.

You are done-calibrating the table.



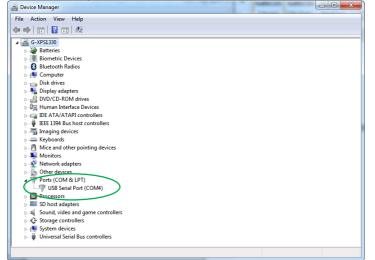
4.2 SOFTWARE INSTALLATION -MICROSOFT WINDOWS

For mac users goto chapter 4.3

4.2.1 DRIVER INSTALLATION

The following steps are necessary to make your printer and the computer able to communicate to each other.

- Plug in the power supply cable. NOTE: without the power cable the electronics doesn't work. It needs the voltage of the purple wire to drive the logic of the board. The power to the rest of the board is controlled by the CPU when needed.
- 2. Plug in the USB cable into the computer
- 3. Your operating system should find the correct drivers automatically
 - a. if the drivers are not found automatically then download drivers from here: <u>http://www.ftdichip.com/Drivers/VCP.htm</u>.
- 4. Go to start->right-click on "Computer"-> click properties -> in left pane click "Device Manager"



Note what COM-port is present. If there are more than one COM ports available unplug the RAMPS USB cable, and re-plug it again. Check what port number is appearing and disappearing. This port number will be used for the next step.

NOTE: If the port is not displayed follow this tutorial: Sometimes windows is still not able to find the port. To fix this follow this tutorial: <u>http://forum.arduino.cc/index.php/topic,107098.0.html</u>



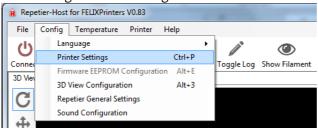
4.2.2 PRINTER SOFTWARE - REPETIER-HOST

The function of Repetier-Host software is to control the printer and processes your CAD files (STL-format) to be printable.

1. Download latest version of Repetier-Host from <u>www.FELIXprinters.com/downloads</u> Navigate to software folder and download **setupRepetierHostFELIXprinters*.exe**

0					•
	FELIX printers	_			
http	://shop.felixprinter	-			
	name •	type	size	date	description
	firmware	<dir></dir>	2 items	12-07-13	
	instruction manuals	<dir></dir>	4 items	12-07-13	
	old	<dir></dir>	-1 items	12-07-13	
	print_files	<dir></dir>	3 items	19-07-13	
	software	<dir></dir>	2 items	27-07-13	

- 2. Run the **setupRepetierHostFELIXprinters*.exe** file and follow the installation instructions.
- 3. Make sure the power cable and USB cable of the printer are connected.
- 4. Start Repetier-host.
- 5. Go to Config -> Printer settings.



In the configuration window press the **Refresh Ports** button.

Printer Settings	
Printer: Felix	•
Connection Printer Print	ter Shape Advanced
Port:	COM1 Refresh Ports
Baud Rate:	250000 🗸
Transfer Protocol:	Autodetect
Receive Cache Size:	63
	From Arduino 1 on the receiving cache was reduced from 127 to 63 bytes!
	munication (Send only after ok)
are stored with every OI	ays correspond to the selected printer at the top. They K or apply. To create a new printer, just enter a new
printer name and press a selected.	apply. The new printer starts with the last settings
	Delete This Printer Setting
	OK Apply Cancel
	OK Apply Cancel

Choose the COM-port which belongs to your printer. This is the same COM-port obtained from previous chapter. The COM1 in the pictures is probably different for your situation.



4.3 SOFTWARE INSTALLATION -MAC OS

- Plug in the power supply cable. NOTE: without the power cable the electronics doesn't work. It needs the voltage of the purple wire to drive the logic of the board. The power to the rest of the board is controlled by the CPU when needed.
- 2. Plug in the USB cable into the computer
- 3. Download Mac-drivers from: <u>http://www.ftdichip.com/Drivers/VCP.htm</u>.
- 4. Download repetier software (.dmg file) from: <u>http://www.repetier.com/download/</u> or from <u>http://shop.felixprinters.com/downloads/index.php?path=software/</u>

FELIX printers	ads/software	software			
name •	type	size	date	description	
🔁 [back]	<dir></dir>		12-07-13		
🗀 old	<dir></dir>	6 items	12-07-13		
sfact slicing profiles	<dir></dir>	1 item	27-07-13		
+ ? Repetier-Host-Mac 0 56.dmg	dmg	12.4 MB	04-09-13		
+ 🕅 setupRepetierHostFELIXPrinters 0 90	.exe exe	37.2 MB	08-07-13		

- 5. Open .dmg file and copy Repetierhost.app to your Application folder
- 6. Download latest printer profiles from

http://shop.felixprinters.com/downloads/index.php?path=software%2Fsfact+slicing+profiles/

FELIX							
http:	//shop.fe	ixprinters.com/	/downloads/	software/	sfact slicing profiles		
	name 🔺	type	size	date	description		
£	[back]	<dir></dir>		04-09-13			
± 🗇	sfact.zip	zip	3.4 MB	10-09-13			

- 7. Extract sfact.zip file (containing 1 folder with 2 subfolders: "sfact" and "sfact_profiles"
- 8. Copy sub-folder "sfact_profiles" to Macintosh HD

1		2		
Macintosh HD	Applications	alterations	cutting	🕨 🚞 Default 🛛 🔹 🕨
Macintosititio	Library	profiles	cutting.csv	Draft Quality
Network	sfact_profiles	►	i extrusion	Enclosure
- Hetholik	🔯 System	-4	extrusion.csv	🚞 High Quality 🕨
	🔝 Users	-4	illing	🕨 🚞 Minimum layerheight 🛛 🕨
			milling.csv	🚞 Normal Quality 🛛 🕨
			skeinforge_profile.csv	Normal quality 80mm
			i winding	Image: Second
			winding.csv	Production exterior support
				Productionsupport+raft
				Production,ort, dense fill
				🚞 Production,rt, normal fill 🕨
				Prodution Full support
				i test ABS
				🚞 test min layerheight 🛛 🕨

- 9. Copy the "sfact" sub-folder to Applications folder (where the Repetierhost.app is as well)
- 10. Open the Repetier-Host Mac Application and go to Printer Settings





11. Configure printer settings:

onfiguration: Defau	lt ‡ Add Delete
Connection	Behaviour Dimension Advanced
Port:	usbserial-AM02607K 🛔
Baud Rate:	250000 ‡
Stop Bits:	1 +
Parity:	None +
Transfer Protocol:	Force ASCII protocol
Receive cache size:	127
Most firmwares have a buffe only have 63 bytes.	r of 127 bytes. The official boards supported by Arduino 1.xx
Use Ping-Pong Com	nmunication (Send only after ok)
receiving buffer. In Ping-Por	nunication, if it sends as many commands as fit into the ig mode, only one command is send at a time. Only after the ie next command is send. Use only if you have problems
receiving buffer. In Ping-Por printer send an ok signal, th	ng mode, only one command is send at a time. Only after the ne next command is send. Use only if you have problems
receiving buffer. In Ping-Por printer send an ok signal, th without Ping-Pong mode. Firmware sends OK	ng mode, only one command is send at a time. Only after the ne next command is send. Use only if you have problems
receiving buffer. In Ping-Por printer send an ok signal, th without Ping-Pong mode. Firmware sends OK Normally a printer sends ok	ng mode, only one command is send at a time. Only after the e next command is send. Use only if you have problems after error
receiving buffer. In Ping-Por printer send an ok signal, th without Ping-Pong mode. Firmware sends OK Normally a printer sends ok	ng mode, only one command is send at a time. Only after the e next command is send. Use only if you have problems after error

Connection Behaviour Dimension Advanced Travel Feedrate: 4800 [mm/min] Z Axis Travel Feedrate: 600 [mm/min] Default Extruder Temperature: 195 [°C] Default heated bed temperature: 55 [°C] Number of Extruder: 1 + Image: Check extruder & heated bed every seconds Image: Don't log temperature requests (M105) Dump area position: X= 125 Y= 0 Z-Min= 20 Go to dispose after job/job kill Image: Disable extruder after job/job kill Image: Disable motors after job/job kill Image: Disable motors after job/job kill Image: Disable motors after job/job kill Image: Seconds [%]	Configuration:	Default		t bbA (‡		
Z Axis Travel Feedrate: 600 [mm/min] Default Extruder Temperature: 195 [°C] Default heated bed temperature: 55 [°C] Number of Extruder: 1 • • Check extruder & heated bed every seconds • Don't log temperature requests (M105) Dump area position: X= 125 • O dispose after job/job kill • Z-Min= • Disable extruder after job/job kill • • Disable motors after job/job kill •	Con	nection	Behaviour	Dimension	Advanced	
Default Extruder Temperature: 195 [°C] Default heated bed temperature: 55 [°C] Number of Extruder: 1 2 Image: Check extruder & heated bed every 3 seconds Image: Don't log temperature requests (M105) 0 Z-Min= Dump area position: X= 125 Y= 0 Z-Min= 20 Go to dispose after job/job kill Image: Disable extruder after job/job kill Image: Disable heated bed after job/job kill Image: Disable motors after job/job kill	Travel Feedrat	[mm/min]				
Default heated bed temperature: 55 [°C] Number of Extruder: 1 ↓ ✓ Check extruder & heated bed every 3 seconds ✓ Don't log temperature requests (M105) Dump area position: X= 125 Y= 0 Z-Min= 20 Go to dispose after job/job kill ✓ Disable extruder after job/job kill ✓ Disable heated bed after job/job kill ✓ Disable motors after job/job kill	Z Axis Travel Feedrate:			600	[mm/min]	
Number of Extruder: 1 Check extruder & heated bed every seconds Check extruder weature requests (M105) Dump area position: X= 125 Y= 0 Z-Min= 20 Go to dispose after job/job kill Disable extruder after job/job kill Disable heated bed after job/job kill Disable motors after job/job kill	Default Extrud	Default Extruder Temperature:			[°C]	
 Check extruder & heated bed every seconds Don't log temperature requests (M105) Dump area position: X = 125 Y = 0 Z-Min= 20 Go to dispose after job/job kill Disable extruder after job/job kill Disable heated bed after job/job kill Disable motors after job/job kill 	Default heated	bed temper	rature:	55	[°C]	
 Don't log temperature requests (M105) Dump area position: X= 125 Y= 0 Z-Min= 20 Go to dispose after job/job kill Disable extruder after job/job kill Disable heated bed after job/job kill Disable motors after job/job kill 	Number of Ext	ruder:		1	•	
Dump area position: X= 125 Y= 0 Z-Min= 20 Go to dispose after job/job kill Disable extruder after job/job kill Disable heated bed after job/job kill Disable motors after job/job kill	🗹 Check extr	uder & heat	ed bed eve	ry 3	seconds	
 Go to dispose after job/job kill Disable extruder after job/job kill Disable heated bed after job/job kill Disable motors after job/job kill 	🗹 Don't log te	emperature	requests (N	M105)		
 Disable extruder after job/job kill Disable heated bed after job/job kill Disable motors after job/job kill 	Dump area po	sition: X=	125	Y= 0	Z-Min= 20	
 Disable heated bed after job/job kill Disable motors after job/job kill 	Go to dispo	ose after job	/job kill			
☑ Disable motors after job/job kill	🗹 Disable ext	ruder after	job/job kil	I.		
	🗹 Disable hea	ted bed aft	er job/job	kill		
Add to comp. printing time: 8 [%]	🗹 Disable mo	tors after jo	b/job kill			
	Add to comp. printing time: 8 [%]					
			0	ĸ	Apply Cancel	



Configuration:	Default	÷)[Add	Delete
Conn	ection Behaviou	r Dimension	Advance	
Home X: X m	in 💠 Home Y:	y min 💲	Home Z:	z min 💲
X Min: 0	[mm] X Max: 25	5 [mm]		
Y Min: 0	[mm] Y Max: 20	5 [mm]		
coordinates can be ne where the printbed it:	ues define the possible egative and outside the self starts. By changing f the print bed, if supp	print bed. Bed left/ the min/max values	front define the	coordinates
Printer type:	Classic Printer			\$
Print Area Width:	255	[mm] Bed Fron	t: 0	[mm]
Print Area Depth:	205	[mm] Bed Left:	0	[mm]
Print Area Height	235	[mm]		
		0*	A metro	Const
		ОК	Apply	Cancel

12. Configure Skeinforge settings under Preferences -> Slicer -> Skeinforge

13. Click "Browse" to direct to the correct files

Application: /Applications/sfact/sfact.py

Craft Utility: /Applications/sfact/skeinforge_application/skeinforge_utilities/skeinforge_craft.py **Python Interpreter:** /usr/bin/pythonw

Python Interpreter: /Applications/Repetier-Host Mac.app/Contents/Resources/pypy.app/bin/pypy **Profiles Directory:** /sfact_profiles/

Configuration panel Host	-	Skeinforge Settings				
▼ Slicer	File Locations					
Skeinforge	Application:	/Applications/sfact/sfact.py	Browse			
Slic3r	Select the Skeinforge ap	oplication python file (skeinforge.py).				
3D visualization	Craft Utility:	/Applications/sfact/skeinforge_i	Browse			
▶ Colors	Select the Skeinforge cra	aft utility python file (skeinforge_craft.py).				
	Python Interpreter:	/usr/bin/pythonw	Browse			
	Select the Python interpr	reter to use (pythonw).				
	Python Interpreter:	s/Resources/pypy.app/bin/pypy	Browse			
	Select the Python interp	reter for slicing. Use pypy for improved spe	ed.			
	Profiles Directory:	/sfact_profiles/profiles	Browse			
		Open Skeinforge homepage				



4.4 CALIBRATE THE Z-DIRECTION/ CONNECT TO PRINTER

To obtain good quality prints it is **essential** that the heated bed is **level** and that the distance between the hot-end and the bed is close enough.

The leveling was done prior to the software installation. So now it is time to calibrate the z-axis height with the z-axis limit switch vane. (If you assembled the printer yourself: Make sure if you have a shining through color printed parts for the printer to apply the tape, tipexx to the limit switch vanes.)

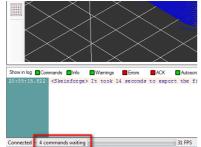
1. Connect to the printer. (The connect button should turn green)



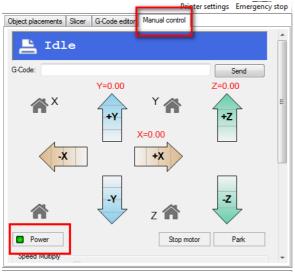
Other checks to see if the printer is connected properly: On the bottom of the repetier host program the following should be displayed



If you see ... commands waiting, press the reset button on the side of the electronics board. Next to the SD card and USB connector.



2. Go to the manual control tab

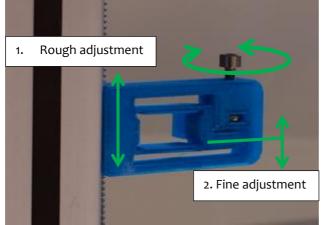




Now it is time to calibrate the z-height:

When doing the following steps, hold your hands on the powercable. Plug it out if something goes wrong.

- Press the Power button. This will turn on the power circuit of the electronics board. Do the following checks to ensure you have connected the wires correctly.
 - Make sure the fan which blows air on top of the hot-end is spinning
 - Make sure the leds of the opto-sensors on the electronics board and on the opto sensors are burning. Make sure the lights of these opto-sensors goes out when they are triggered. So if the the flanges go into the limit-switch the light should turn off.
- Make sure the bed is at least 5 cm from the hot-end.
- Press Home X, then move the x axis back and forth. The axis will only move in positive direction if the Home X button is not pressed.
- Press Home Y, move the y axis back and forth.
- Press Home Z
- The distance between the table and hot-end is probably too large.



- Turn the screw in such a way that the flexible vane mechanism goes downwards. Do this approx. till ¾ of the possible stroke. Move the complete part a little bit up and press Home Z again.
- Repeat this until the table is approx. 3 mm from the nozzle. Now fix the bracket to the frame and start homing again. Now repeat this procedure to get the nozzle closer and closer by turning the little screw as shown in the picture above.
- Do this a couple of times until the distance is less than the thickness of a piece of normal paper.

Scroll down the manual control window.

Extruder	Printbed
Heat Extruder	Heat Printbed
Extruder 1 💌 25.00°C / 195 🌩	Temp. 24.20°C / 55 🚔
Speed [mm/min] 500 🚔	Fan
Extrude [mm] 5 🚔 🛶	Fan Output 100.0%
Retract [mm] 50	
Debug Options	
Cecho Info Ce	rrors OK Dry Run

Check if the switchable fan mounted to the airduct is working.

Move the slider to 100% and press the fan button

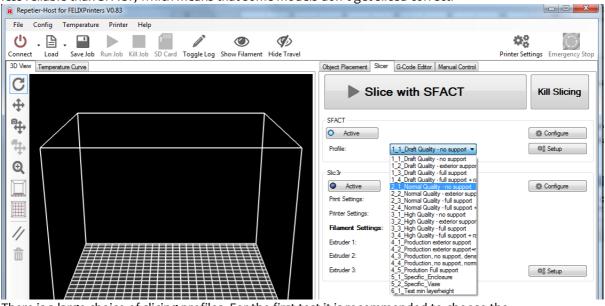
You are almost ready to do your first print, please proceed to the next section.

14. The software is configured for printing and it is now time to slice and print your first object. Get your test file from here:

http://shop.FELIXprinters.com/downloads/index.php?path=print_files%2Ftest_print_files/ . In this tutorial the smallest file is used. _40x10.STL.



Go to the **Slicer** tab. You'll see two type of slicers. The first one is SFACT and the second one is Slice3r. SFACT is the preferred choice and has optimized profiles for the felixprinter. Slice3r is a faster slicer, but is less reliable than SFACT, which means that some models don't get sliced correct.



There is a large choice of slicing profiles. For the first test it is recommended to choose the **2 1 Normal Quality** profile.

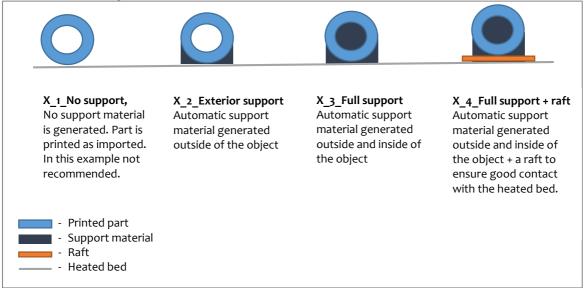
Short explanation of the slicing profiles:

Profile 1_1 to 3_4: are profiles setup for everyday printing.

Profile 4_1 to 4_5: are profiles optimized for our production parts. These are the profiles used to produce the printed parts of your printer. When printer upgrades are provided, these can be used to slice your parts. **Profile 5_1 to 5_2:** are used for specific cases

Profile 6_1 and further: are used for testing purposes.

The structure of the profiles 1 to 4 is done like this:



The profiles are easy to adjust and tweak yourself for further improvement. To do this just click the configure button



This will show a very elaborate amount of settings to tweak. Don't worry every setting is well documented. If you are interested to know more just click the question mark button as indicated in the figure below.

76 filament roll holder pt1_v3.STL - Skeinforge Settings	
File Analyze Craft Help Meta Profile	
Profile Type: Extrusion	
· · · · · · · · · · · · · · · · · · ·	
Profile Selection: 1 Draft Quality - no support-	
Analyze Craft Help Meta Profile	
Craft ?	
Alteration Bottom Carve Chamber Clip Comb Cool Dimension Export Fill	
Fillet Home Hop Inset Jitter Lash Limit Multiply Oozebane Preface	
Raft Scale Skint Smooth Speed Splodge Stretch Temperature Tower	
Unpause Widen Wipe	
Raft ?	
E. C. DO	
✓ Activate Raft	-
Add Raft, Elevate Nozzle, Orbit:	
- Support -	
Where to add support: None —	
Add support if flatter than (degrees):	
Cross Hatch instead of Lines	
Interface/Support Lines Density (ratio):	
Interface/Support Layer Thickness over Layer Thickness: 1.0	
Support Feed Rate mm/sec:	
Support Flow Rate (scaler):	
Support Gap over Perimeter Extrusion Width (ratio):	
Raft/Support extension in (%):	
Raft/Support extension in(mm):	
- Name of Support Macro files (gcode) -	
Name of Support End File: support_end.gmc	
Name of Support Start File: support_start.gmc	
- Print Adhesion to Printbed Objects first layer - Extra Nozzle clearance over Object(ratio): 0.0	
Extra Nozzle clearance over Object(ratio):	
- Interface -	
Interface Layers (integer): 0	
	-
Skeinforge ? Cancel Save All	

15. Now back in the repetier main interface make sure the SFACT slicer is activated and select one of the profiles.

Slice with SFACT	Kill Slicing
SFACT Active Profile: 1_1_Draft Quality - no support	Configure

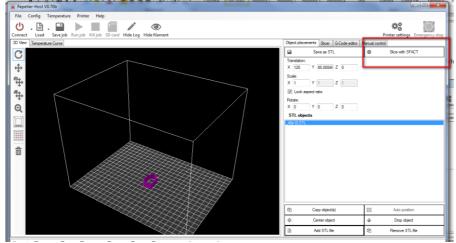
16. Now it is time to slice our first object.



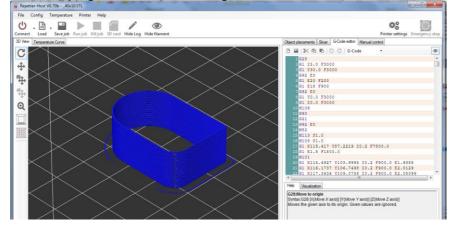
		rinde seeings energency stop
	Object Placement Slicer G-Code Editor Manual	I Control
	Save as STL	Slice with SFACT
	Translation	
	X Y Z	
	Scale X Y Z	
	U Lock Aspect Ratio	
	Rotation	
	X Y Z	
	STL Objects	
Repetier-Host for FELIXPrinters V0.83		
File Config Temperature Printer Help		
じ 🕒 🕨 🕨 🖉 🦉 🥥		
Connect Load Save Job Run Job Kill Job SD Card Toggle Log Show Fili		
3D View Tongo Loa file		
C	Copy Object(s)	Autoposition
*	Center Object	↓ Drop Object
+	Add Object	Remove Object

Press the *Load button* or in the Object placement tab, *Add Object button*. Then navigate to the folder where you downloaded the _40x10.STL file or any other STL file.

17. Slice this file and prepare it to print. Press the Slice with SFACT button



When the program is done after slicing the interface should look like this:



You have now sliced your first object and are ready to go to the next step.



5 IT'S TIME FOR PRINTING!

After all the hard work of the assembly and setting up the machine it is time to get some reward by means of your first successful print.

Before pressing the "Print" button make sure of the following

In the manual control window do the following.

- Heat up the extruder to 195 degC
- Heat up the heated bed to 55 degC
- Move the table down 10mm

If the extruder and heated bed are warmed up, check or make sure that the following is true:

- Printer axes can move without obstructions
- Remove all plastic residues on the heated bed, preferably with the supplied tweezers
- Degreased heated bed surface.
- When all axes are homed the hot-end is not touching the table.

Move down the table 10mm and insert the supplied PLA filament in the extruder.

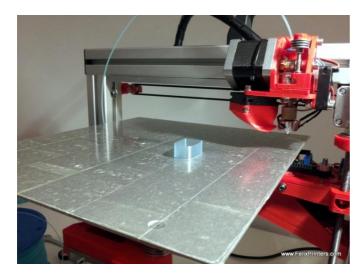
Run the extruder until a steady flow of plastic comes out.

When there is not a continuous flow coming out of the nozzle, make sure the extruder arm is properly tensioned. Turn the m4 bolt clockwise to put more tension on the filament, so the filament will be pulled into the hot-end better. But watch out, too tight and the motor will have a hard time to turn and the filament might be squashed so wide that it gets clogged into the hot-end.

When these steps are OK, you are ready to press that print button.



If the calibration was done ok the print should finish without any problem. The most probable cause of failure could be the wrongly adjusted z-height of the first layer.





If the print looks like the picture above than congratulations your printer is completed!!

If the print fails, it usually because the distance of the bed and nozzle is too large. Try to adjust the z-axis limit switch vane to get the distance closer.





IMPORTANT info:

To keep the hot-end running as long as possible, let the filament run through a dust collector like a small piece of sponge. The filament picks quite a lot of dust due to static charge or dirt from the factory. This will all enter the hot-end and partially stick in there and finally clog the nozzle. When this happens the hot-end needs to be cleaned out when hot from both sides. A tutorial for this is available on the forum on the website.

6 FAQ

Q: Which hot-end nozzle temperature do you recommend?

A: For small detailed parts we recommend to print as cold as possible 180 to 190 degC, but for our production prints we print with an as high as possible temperature (195-200 degC), because that increases strength of the parts.

The optimal temperature depends on the type of filament used. When using PLA check if the temperatures of the hotend and the heated bed are between 180-210 and 30-60 degrees C respectively. When using ABS these temperatures should be somewhere around 210-250 and 70 – 100 degrees respectively. The heated bed temperatures can be much lower with painters tape. Try only using PLA or ABS as filament. If you wish to use any other kind of material, consult FELIXprinters first.

Additional note:

Each supplier provides PLA with slightly different properties, even different colors have different properties. To find the optimal temperature for optimal extrusion, start with a low temperature. Then go up slightly. When the temperature is too high, you might hear some pops and sisses coming from the hot-end. When the temperature is too low the extruder motor will have a hard time extruding. When printing at high speed, the temperature of the filament should be a little higher.

Q: How would you recommend changing the filament?

It is possible to change filament in the following ways.

- 1. Retract/Replace. This is the safest way to change filament.
- Retract the old filament at a high speed, 1000mm/min for 100mm. The high speed prevents development of a long string which can potentially jam the hot-end.
- Now extrude the new filament 50mm at a time at low speed 200mm/min, until filament comes out of the nozzle.
- 2. Feed through. In this method filament is cut off near the extruder.
- Cut the filament off as straight as possible. The new filament will push it down, and if cut of scew, the new filament will slip of the to be pushed filament resulting in a extruder jam.
- Extrude the filament long enough at a low speed 200mm/min. When the filament is just cut off above the extruder entrance, 50mm should be sufficient to push the new filament into the hot-end.
- Again extrude it 50mm to flush out the old filament.

Q: How to elongate the lifetime of the hot-end?

A: The hot-end is robust, seldomely have we experienced a jam or failed operation. But because we print 24/7 we experienced that the hot-end stopped working after 2-3 months. The reason for that is a contaminated hot-end. Ways to prevent this from happening.

- Make sure the filament enters the hot-end is clean from dust. Do this by letting it run through a piece of sponge before it enters the hot-end. You will be surprise how much dust there will be there after a 5 hour print. That would of all entered the hot-end and form a layer of contaminants, which isolates that heat. from going into the filament
- Do not use too high temperatures. This will make the filament decompose and contaminate the inside of the nozzle.
- Do not leave the hot-end heated for hours. The filament might decompose after leaving it at high temperatures and this will leave a layer of contaminants behind in the hot-end nozzle
- Use good quality filament.



7 MAINTENANCE/OPTIMAL OPERATIONAL TIPS

The FELIXprinter is an easy to product to maintain and clean. To keep enjoying your FELIXprinter and ensure optimal print performance, regular maintenance is very important.

7.1 GENERAL TIPS FOR OPTIMAL OPERATION

- Make sure filament that enters the hot-end is as clean as possible from dust. Do this by letting it run through a piece of sponge before it enters the hot-end. You will be surprise how much dust there will be there after a 5 hour print. That would of all entered the hot-end and form a layer of contaminants, which isolates heat from going into the filament
- Do not use too high temperatures. This will make the filament decompose and contaminate the inside of the nozzle.
- Do not leave the hot-end heated for hours. The filament might decompose after leaving it at high temperatures and this will leave a layer of contaminants behind in the hot-end nozzle
 Use good quality filament.

7.2 CLEANING

- To ensure good bed adhesion of prints we recommend cleaning the heating bed with spirit, alcohol, thinner or nail polish remover. We recommend doing this before or after each print, especially for long prints.
- Be careful with getting any liquids onto the electric board, it can damage the electronics permanently.
- Dust the printer off with a moist piece of cloth.

7.3 REGULAR MAINTAINANCE

- Lubricate the vertical spindle and the lineair railings with a lubricant, we recommend doing this every 3 months.
- After some time the toothbelt might loose a little tension. Tighten the screw in the belt tensioning part until a healthy tension is back on the belt. For an indication of how to tension the belt check out this video: <u>http://www.youtube.com/watch?v=dpS6nWn5rE8</u>

-

7.4 PRECAUTIONS

To prevent that you will be unable to print, we recommend printing out the following spare parts.

- Extruder arm
- Airduct

GOTO: <u>http://shop.felixprinters.com/downloads/</u> then navigate to print_files/spare_parts Search for **Extru_arm_v6_F_1_5.STL** and **print_assy_5_F1_5_export.gcode**



8 TROUBLESHOOTING

This chapter helps to troubleshoot common problems with the printer. Each common issue is described in a table. Follow from top to bottom to get to the solution in the most likely way.

PROBLEM: Stopped extrusion after x-layers/Skipped layers/weak strength of parts/Extruder jammed.				
Possible cause	Possible solution			
1. Is temperature setting OK?	Recommended hot-end temperatures are: PLA: 180 – 200 degC ABS: 210 -240 degC			
	Too hot extrusion causes two things. Filament in the nozzle tip gets very fluid. When there are fast extrusions, the molted filament could creep up the barrel and causes jams, because it cools down and solidifies.			
	The temperature of the cold zone will get critically hot and the filament starts to melt too fast.			
	Too cold extrusion, can cause the filament to slip over the extruder wheel due to the extremely high required force to extrude the filament.			
2. Is fan blowing on top of hot-end working?	The fan blowing on top of hot-end is working. When there is loose contact the fan might stop working on some points of the movement. This could cause the top part of the hot-end to get too hot.			
3. Ambient temperature OK?	Ambient temperature must be between 15 to 30 degC			
4. Filament quality within tolerance?	Check if the filament diameter is within the 1.6 to 1.8mm. Somethimes filament substance is not consistent, try different filament to see if it solves the issue			
 Are all bolts to assemble the extruder assemble tightenend sufficiently? 	Make sure bolts are all tightened sufficiently.			
6. Extruder arm tension OK?	The extruder arm must be able to exert enough pressure on the filament. Turn the bolt in front of the extruder clockwise for more pressure. Turn it counterclockwise to exert less pressure. When too much pressure on the arm the filament will be squashed too wide and cause a lot of friction inside the hot-end and eventually might get stuck.			
7. Extruder arm in good shape?	Check if the extruder arm is not broken. Replace if broken or deformed too much.			
8. Contaminents inside the hot- end.	Filament attracts a lot of dust, which without filtering all has to go through the tiny nozzle. In time this could cause, a layer of dirt inside which acts as a thermal barrier, preventing the filament to melt properly. Try to clean nozzle exit with 0.35mm drill. Guitar string, or other thin wire to clean nozzle. If this doesn't work there is a large contamination from the inside. Take the hot-end apart and clean it carefully with a 2mm drill from the inside. This will only work when the hot-end is hot. Please follow the instructions dowloadable here: http://shop.FELIXprinters.com/downloads			
 The hot-end parts are not assembled good enough 	When parts are too loosely mounted filament could leak through the components.			
10. Fabrication error in hot-end	It could be that due to fabrication tolerances the hot-end parts are not fully up to spec, maybe not aligned perfectly or the holes are not the same. Most issues occur with the PEEK middle isolation part. Try to post drill it with a 2mm drill.			



PROBLEM: Objecst don't stick to the heated build platform

Possible cause	Possible solution
1. Is the bed clean?	For good bed adhesion of the object the bed must be clean from dirt, dust
	and grease. A recommended cleanser is spirit/alcohol/thinner.
2. Is the heated bed on?	The recommende bed temperature for PLA is 55 degC
3. Is the bed level?	Essential for good bed adhesion is that the bed is level. Make sure the bed
	is leveled properly, the distance between nozzle and bed must be the same
	everywhere.
4. Distance from head to bed ok?	Make sure the distance between bed and hot-end tip is close enough for
	first layer. Adjust finetuning mechanism accordingly.
5. Is the printspeed of the first	Try reducing the speed for the first layer
layer low enough?	
6. Is the bed flat	When the bed is not flat, due to assembly, damage or from the factory, it is
	impossible to have the same distance from bed to nozzle over the whole
	surface. If this is the case, try to bend the bed by hand. Make sure you
	don't introduce forces into the bearing of the y-axis.

PROBLEM: Bad print quality		
Symptom	Possible solution	
Changing slicing settings in repetier-host don't have effect.	Make sure you have selected/activated the correct slicer settings. SFACT is the slicer of preference. Slic3r is not configured out of the box.	
Circles are not round/Dimensions differ	Check belt tension Make sure y-axis bearing is fastened enough to the z-axis carrier and also make sure the 4 bolts are mounted with washers. Are pulley's setscrews fastened?	
Parts with sharp corners have large vibrations/waves	Make sure all parts are fastened correctly	
The part sags after a few layers; this happens mostly to smaller parts with thin walled features.	The temperature of the filament is way too high. The extrusion is not good enough. Make sure nozzle exit is clean and also extrusion mechanism is working properly. Slow down the printspeed to give part more time to cool down.	
Quality of small parts is really bad	Decrease temperature Slow down speed. Print multiple parts in the same print. Use the multiply plugin in SFACT/Skeinforge.	



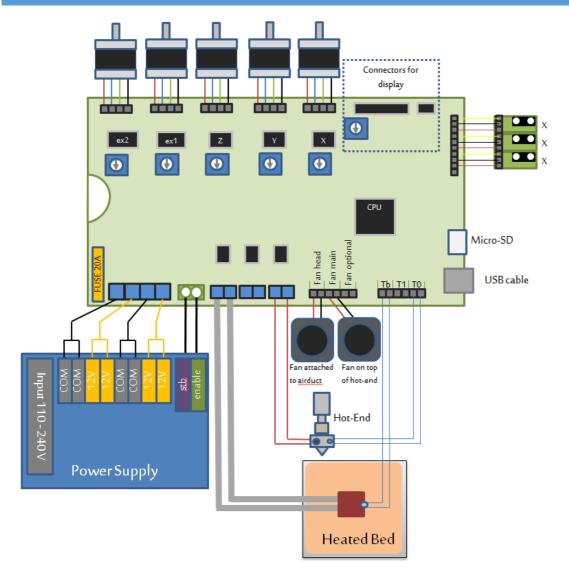
9 SAFETY

To safely operate the FELIXprinter, we advise to keep the following safety recommendations in mind:

- 1. Keep children under the age of 14 out of reach of the FELIXprinter
- 2. Caution with any moving parts that move in the X, Y and Z direction. At the end of each moving part there is a pinching hazard.
- 3. Watch out for any other non-protected sharp edges of the printer.
- 4. Don't lay objects on the heated bed that are not being printed, not even when the printer is turned off.
- 5. Only use the materials polyactide (PLA), Acrylonitrile butadiene styrene (ABS) or Arnitel as printing material. Consult FELIXprinters if you want to use a different material.
- 6. FELIXprinters is only suitable for professional use.
- 7. When removing or feeding material to the hot end, wearing heat resistant gloves is recommended.
- 8. Only operate the FELIXprinter in a sufficient ventilated environment (fumes from ABS and PLA aren't toxic, but can cause an irritable respiratory).
- 9. Don't lean on the FELIXprinter when it is operating.
- 10. Make sure all moving parts can move without any obstructions.
- 11. Don't remove any objects from the hot plate while the printer is still printing objects.
- 12. Don't transport the FELIXprinter when it is in operation.
- 13. Do not use a different power supply than the provided power supply, it can be dangerous and cause electronical malfunctions.
- 14. Use the FELIXprinter in a dry environment.
- 15. Use the FELIXprinter on a stable and leveled surface.
- 16. When moving the FELIXprinter only use the handle on top.
- 17. Turn off the FELIXprinter when errors occur.
- 18. When operating the FELIXprinter, be carefull with long hair and loose clothes.
- 19. When unattended, turn off the FELIXprinter.
- 20. Place the FELIXprinter on a table/Desk or something with a similar height. This will keep it safe from small children.



10 APPENDIX: ELECTRONICAL SCHEMATICS





11 APPENDIX: MATERIAL DATA SAFETY SHEET

11.1 PLA

Hazards Identification

Appearance:	Clear, translucent, opaque, pellets.
Physical state:	Solid
Odor:	Sweet

Potential health effects:

Eye contact: Contact with eyes may cause irritation. Skin contact: Substance may cause slight skin irritation. Ingestion: Ingestion may cause gastrointestinal irritation, nausea, vomiting and diarrhoea. Inhalation: Inhalation of dust may cause shortness of breath, tightness of the chest, a sore throat and cough. Low hazard for usual industrial or commercial handling. Target organ effects: There were no target organ effects noted following ingestion or dermal exposure in animal studies. Sensitization: Did not cause sensitisation on laboratory animals Flammability: Fine dust dispersed in air may ignite.

First-aid measures

Eye contact: Rinse immediately with plenty of water, also under the eyelids, for at least 15 minutes. Call a physician immediately.

Skin contact: Rinse immediately with plenty of water for at least 15 minutes. If skin irritation persists, call a physician. Cool skin rapidly with cold water after contact with hot polymer.

Inhalation: Move to fresh air. Call a physician immediately.

Ingestion: Drink water as a precaution. Never give anything by mouth to an unconscious person. Do not induce vomiting without medical advice. Call a physician immediately.

Notes to physician: Treat symptomatically.

Fire Fighting Measures

Flammability: Autoignition temperature: 388°C Flammability Limits in Air Flammable limits in air - lower (%): Not determined Flammable limits in air - upper (%): Not determined

Suitable extinguishing media: Foam. Water. Carbon dioxide (CO2). Dry chemical. Alcohol resistant foams are preferred if available. General-purpose synthetic foams (including AFFF) or protein foams may function, but much less effectively. Extinguishing media which must not be used for safety reasons: No information available

Hazardous decomposition products: Burning produces obnoxious and toxic fumes Aldehydes Carbon monoxide (CO) carbon dioxide (CO2)

Special protective equipment for firefighters: As in any fire, wear self-contained breathing apparatus pressure-demand, MSHA/NIOSH (approved or equivalent) and full protective gear.

Under fire conditions: Cool containers / tanks with spray water. Water mist may be used to cool closed containers.

Other information: Fine dust dispersed in air may ignite. Risks of ignition followed by flame propagation or secondary explosions shall be prevented by avoiding accumulation of dust, e.g. on floors and ledges.

Handling and Storage

Safe handling advice: Avoid contact with skin and eyes. Avoid dust formation. Workers should be protected from the possibility of contact with molten material during fabrication. Low hazard for usual industrial or commercial handling. Use personal protective equipment.

Storage:

Store in cool place. Keep at temperatures below 122F (50 °C). No special restrictions on storage with other products.

Toxicological Information

Principle Routes of Exposure: Eye contact. Skin contact. Inhalation. Ingestion. Acute toxicity: There were no target organ effects noted following ingestion or dermal exposure in animal studies.



Local effects: May cause eye/skin irritation. Product dust may be irritating to eyes, skin and respiratory system. Caused mild to moderate conjuctival irritation in eye irritation studies using rabbits. Caused very mild redness in dermal irritation studies using rabbits (slightly irritating). Ingestion may cause gastrointestinal irritation, nausea, vomiting and diarrhoea.

Long term toxicity: Did not cause skin allergic reactions in skin sensitization studies using guinea pigs. Specific effects: May cause skin irritation and/or dermatitis. Ingestion may cause gastrointestinal irritation, nausea, vomiting and diarrhoea. Inhalation of dust may cause shortness of breath, tightness of the chest, a sore throat and cough. Burning produces irritant fumes.

Target organ effects: There were no target organ effects noted following ingestion or dermal exposure in animal studies.

Skin: LD50/dermal/rabbit > 2000 mg/kg Ingestion: LD50/oral/rat > 5000 mg/kg.

Ecological Information

Bioaccumulation: Does not bioaccumulate. Inherently biodegradable. Ecotoxicity effects: EC50/72h/algae > 1100 mg/L

Disposal Considerations

Waste from residues / unused products: In accordance with local and national regulations. Do not contaminate ponds, waterways or ditches with chemical or used container. Contact manufacturer.

THE COMPANY HAS NO CONTROL OVER THE MANAGEMENT PRACTICES OR MANUFACTURING PROCESSES OF PARTIES HANDLING OR USING THIS MATERIAL. THE INFORMATION PRESENTED HERE PERTAINS ONLY TO THE PRODUCT AS SHIPPED IN ITS INTENDED CONDITION.

(Composition/Information On Ingredients).

Contaminated packaging: Empty remaining contents. Do not re-use empty containers. Empty containers should be transported/delivered using a registered waste carrier to local recyclers for disposal.



11.2 ABS

Hazards Identification

This product is not classified as dangerous according to EC criteria.

First-aid measures

Eye Contact: Flush eyes with plenty of water; remove contact lenses after the first 1-2 minutes then continue flushing for several minutes. Only mechanical effects expected. If effects occur, consult a physician, preferably an ophthalmologist.

Skin Contact: If molten material comes in contact with the skin, do not apply ice but cool under ice water or running stream of water. DO NOT attempt to remove the material from skin. Removal could result in severe tissue damage. Seek medical attention immediately.

Inhalation: Move person to fresh air; if effects occur, consult a physician.

Ingestion: If swallowed, seek medical attention. May cause gastrointestinal blockage. Do not give laxatives. Do not induce vomiting unless directed to do so by medical personnel.

Notes to Physician: If burn is present, treat as any thermal burn, after decontamination. No specific antidote. Treatment of exposure should be directed at the control of symptoms and the clinical condition of the patient.

Fire Fighting Measures

Extinguishing Media: Water fog or fine spray. Dry chemical fire extinguishers. Carbon dioxide fire extinguishers. Foam. Fire Fighting Procedures: Keep people away. Isolate fire and deny unnecessary entry. Soak thoroughly with water to cool and prevent re-ignition. If material is molten, do not apply direct water stream. Use fine water spray or foam. Cool surroundings with water to localize fire zone. Hand held

dry chemical or carbon dioxide extinguishers may be used for small fires

Special Protective Equipment for Firefighters: Wear positive-pressure self-contained breathing apparatus (SCBA) and protective fire fighting clothing (includes fire fighting helmet, coat, trousers, boots, and gloves). If protective equipment is not available or not used, fight fire from a protected

location or safe distance.

Unusual Fire and Explosion Hazards: Pneumatic conveying and other mechanical handling operations can generate combustible dust. To reduce the potential for dust explosions, do not permit dust to accumulate. Dense smoke is produced when product burns.

Hazardous Combustion Products: During a fire, smoke may contain the original material in addition to combustion products of varying composition which may be toxic and/or irritating. Combustion products may include and are not limited to: Nitrogen oxides. Carbon monoxide. Carbon dioxide.

Combustion products may include trace amounts of: Styrene. Hydrogen cyanide

Handling and Storage

Handling

General Handling: No smoking, open flames or sources of ignition in handling and storage area. Good housekeeping and controlling of dusts are necessary for safe handling of product. Avoid breathing process fumes. Use with adequate ventilation. When appropriate, unique handling

information for containers can be found on the product label. Workers should be protected from the possibility of contact with molten resin. Do not get molten material in eyes, on skin or clothing. Pneumatic conveying and other mechanical handling operations can generate combustible dust. To

reduce the potential for dust explosions, electrically bond and ground equipment and do not permit dust to accumulate. Dust can be ignited by static discharge.

Storage

Store in accordance with good manufacturing practices

Personal Protection

Eye/Face Protection: Use safety glasses. If there is a potential for exposure to particles which could cause eye discomfort, wear chemical goggles. If exposure causes eye discomfort, use a full-face respirator. Use safety glasses. Safety glasses should be consistent with Directive 89/686/EEC

Category 2. If there is a potential for exposure to particles which could cause eye discomfort, wear chemical goggles. Chemical goggles should be consistent with EN 166 or equivalent. If exposure causes eye discomfort, use a full-face respirator.

Skin Protection: No precautions other than clean body-covering clothing should be needed. Hand protection: Chemical protective gloves should not be needed when handling this material. Consistent with



general hygienic practice for any material, skin contact should be minimized. Use gloves with insulation for thermal protection (EN 407), when needed. Use gloves to protect from mechanical injury. Selection of gloves will depend on the task.

Respiratory Protection: In dusty or misty atmospheres, use an approved particulate respirator. Use an approved airpurifying respirator when vapors are generated at increased temperatures or when dust or mist is present. Use the following CE approved air-purifying respirator: When dust/mist are

present use a/an Particulate filter, type P2. When combinations of vapors, acids, or dusts/mists are present use a/an Organic vapor cartridge with a particulate pre-filter, type AP2.

Ingestion: Use good personal hygiene. Do not consume or store food in the work area. Wash hands before smoking or eating.

Engineering Controls

Ventilation: Good general ventilation should be sufficient for most conditions. Local exhaust ventilation may be necessary for some operations

Toxicological Information

Acute Toxicity

Ingestion

Very low toxicity if swallowed. Harmful effects not anticipated from swallowing small amounts. May cause choking if swallowed.

Estimated LD50, Rat > 5,000 mg/kg

Eye Contact

Solid or dust may cause irritation or corneal injury due to mechanical action. Elevated temperatures may generate vapor levels sufficient to cause eye irritation. Effects may include discomfort and redness.

Skin Contact

Essentially nonirritating to skin. Mechanical injury only. Under normal processing conditions, material is heated to elevated temperatures; contact with the material may cause thermal burns.

Skin Absorption

No adverse effects anticipated by skin absorption. Estimated LD50, Rabbit > 2,000 mg/kg Inhalation

No adverse effects are anticipated from single exposure to dust. Vapors/fumes released during thermal processing may cause respiratory irritation.

Repeated Dose Toxicity

Additives are encapsulated in the product and are not expected to be released under normal processing conditions or foreseeable emergency.

Ecological Information

CHEMICAL FATE

Movement & Partitioning

No bioconcentration of the polymeric component is expected because of its high molecular weight. In the terrestrial environment, material is expected to remain in the soil. In the aquatic environment, material will sink and remain in the sediment.

Persistence and Degradability

This water-insoluble polymeric solid is expected to be inert in the environment. Surface photodegradation is expected with exposure to sunlight. No appreciable biodegradation is expected.

ECOTOXICITY

Not expected to be acutely toxic, but material in pellet or bead form may mechanically cause adverse effects if ingested by waterfowl or aquatic life.

Disposal Considerations

For uncontaminated material the disposal options include mechanical and chemical recycling or energy recovery. In some countries landfill is also allowed. For contaminated material the options remain the same, although additional evaluation is required. For all countries the disposal methods

must be in compliance with national and provincial laws and any municipal or local by-laws. All disposal methods must be in compliance with the EU framework Directives 91/156/EEC, 91/689/EEC and their subsequent adaptations, as implemented in National Laws and Regulations, as well as EU Directives dealing with priority waste streams. Transboundary shipment of wastes must be in compliance with EU Regulation 259/93 and subsequent modifications.



12 APPENDIX: FIRMWARE INSTALLATION

Sometimes the firmware of the electronics board can get updated; this chapter explains how to do it. For your first print this chapter is not necessary.

Go to the FELIXprinters <u>http://www.FELIXprinters.com/downloads/</u> and follow the download links to get all the required software.

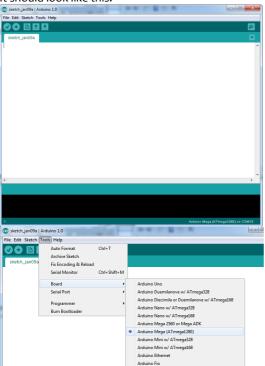
This step requires the following software:

- Arduino, <u>www.arduino.cc</u> platform to upload firmware to the printer.
- FELIXprinter firmware (check the revision of the printer). Contains printer settings for correct operation of your Felix printer.

Steps to upload new firmware to the FelixPrinter

1. Start Arduino software

It should look like this:



Select the correct platform:

Tools -> Board-> Arduino Mega(ATmega2560 or MEGA ADK) for FELIXprinters electronics board. The old arduino ramps board required the ATmega1280 sometimes.

		-0-		
💿 sketch_jan09a Ard	uino 1.0			
File Edit Sketch Too	ls Help			
sketch_jan09a	Auto Format Archive Sketch Fix Encoding & Reload	Ctrl+T		
	Serial Monitor	Ctrl+Shift+M		
	Board	+_		
	Serial Port	•	✓ COM4	
	Programmer Burn Bootloader	۱. ۲		
			a 	

Select the correct Serial Port which you've noted earlier Tools -> Serial Port -> COM...



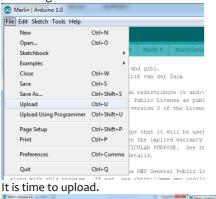
le Edit Sketch Tools Help	
New	Ctrl+N
Open	Ctrl+0
Sketchbook	۰.
Examples	+
Close	Ctrl+W
Save	Ctrl+S
Save As	Ctrl+Shift+S
Upload	Ctrl+U
Upload Using Programmer	Ctrl+Shift+U
Page Setup	Ctrl+Shift+P
Print	Ctrl+P
Preferences	Ctrl+Comma
Quit	Ctrl+Q

Extract the downloaded FelixPrinter firmware to some folder.

Open this folder through the Arduino interface and click on the Marlin.INO file.

Marlin Arduino 1.0	and Physics			-			x
File Edit Sketch Tools	Help						
							ø
Marlin Configurat	tion.h EEPROMwrite.h	Marlin.h	MarlinSerial.cpp	MarlinSerial.h	Sd2Card.cpp	Sd2Card.h	▼ Bd
Preprap firmwar Copyright (C) 2013 This program is fr it under the terms the Free Software (at your option) of	e based on Sprinter an l Camiel Gubbels / Eri ree software: you can s of the GHU General P Foundation, either ve any later version. istributed in the hope	k van der : redistribu ublic Licen rsion 3 of	te it and/or mod nse as published the License, or	by			• 0

A new window will pop-up, with all the source firmware files. All the settings for the FelixPrinter to work correctly are configured. Feel free to browse around the files to get a better understanding of how it all works.



Marin Arduino 1.0	C Merin Arduino 1.0	Marin Arduino 1.0
ile Edit Sketch Tools Help	File Edit Sketch Tools Help	File Edit Sketch Tools Help
Marin Configuration EEPROMentan Marin h Marinderial cop Marinderial h Sd2Cerd cop Sd2Cerd h = 3c	Marin Configuration h EEPROMivitian Marin h MarinBenal opp MarinBenal St2Cant op Bd2Cant h =3d	Marin Corrégoration.h EEPROMerite.h Marin.h WarinBeriat.cpp MarinBeriat.h 8d3Card.cpp 8d3Card.h =30
/haning birt the endettp, then retracts by this distance, before it tries to slowly long equin:	7/Among hirs the entrys, then extracts by this distance, before it tries to sleedy husp equin: #editase XUME_RETAINTOR 50 = #editase XUME_VENANCTOR 5 #editase XUME_VENANCTOR 1	(Johan) hims the matter, then retrarts by this distance, before it tries to slowly long spain: whetlaw SJMENTENATIM i whetlaw TJMENTENATIM i whetlaw TJMENTENATIM i
Hefine AXIS_HELATIVE_HIGES (false, false, false)	fortine AUIS_FELATIVE_MINES (faire, faire, faire, faire)	Wording KUS_MELATIVE_HOURS (false, false, false, false)
Gefine BAX_STEF_FFEQUENCY 40010 // New step frequency for Ultianker (5100 pps / half step)	#define NAX_STEP_FFEIUERCY 40000 // Nax step frequency for Ultimater (SOID pps / half step)	#define NAC_TIXP_FREQUENCY 40000 // Hax step frequency for Ultimaker (5010 pps / half step)
// default settings	// default rettings	// defoult settings
Weinis ENDIT_COLS_TITE_PL_NUMIT (M.19994, M.19994, M.19904, M.19904, M.19904 // drawls star //scine ENDIT_COLS_TITE_PL_NUMIT (00, 00, 52, 20000) // (m./sci // (m./sci Media ENDIT_COLS_TITE_PL_NUMIT (00, 00, 52, 20000) // (m./sci // (m./sci Media ENDIT_COLS_TITE_PL_NUMIT (00, 00, 52, 20000) // (m./sci // (m./sci Media ENDIT_COLS_TITE_PL_NUMIT (00, 000, 1// N/); (n./sci (m./sci // (m./sci	Wetches DERMIT_LOED_STUDDE UNE_INST. (Nr. 199904, 75.199904, 200.464,169) // default sto: //sofiche DERMIT_LOED_STUDDE UNE_INST. (Nr. 19904, 75.19904, 200.464,169) // default sto: //sofiche DERMIT_NGL_TELEPINT (S0, 50, 55, 20008) // sol/sol Marine DERMIT_NGL_TELEPINT (S0, 50, 55, 20008) // sol/sol Marine DERMIT_NGL_TELEPINT (S00, 500, 10008) // sol/sol	<pre>federate EFRATL_ACI_STIPS_FED_URIT [04.109004, N.19904, 100.66,140] //Deficie EFRATL_CAL_STIPS_FED_FED_URIT (04.0, 03.03.03.01) //Deficie EFRATL_STIPS_FED_URIT (04.0000) //DEficie EFRATL_STIPS_FED_URIT (04.00000) //DEficie EFRATL_STIPS</pre>
Hefine HEFMILT_ACCELEPATION 1000 // 2010 %, Y, Z and E max acceleration in ma/s*2 for printing i Hefine HEFMILT_HEFMACT_ACCELEPATION 1000 // 7000 %, Y, Z and E max acceleration in ma/s*2 for r setrects	fortime DEFNULT_ACCELENATION 1000 // 2000 X, Y, Z and E max acceleration in mm/s*2 for reinting s fortime DEFNULT_METRACT_ACCELENATION 2000 // 7000 X, Y, Z and E max arceleration in mm/s*2 for r retracts	#define DEFAULT_ACCELEPATION 1000 // 2000 X, T, 2 and E max acceleration in mm/s*2 for printing #define DEFAULT_METHACT_ACCELEPATION 2000 // 7010 X, Y, I and E max acceleration in mm/s*2 for x retracts
Gefine HEFMILT_HIEVENHIPZIGATE 0.0 // minimum fredrate Gefine HEFMILT_NIEVENHIPEIGATE 0.0	forfine lEFAULT_REIGHTFEIGATE 0.0 // minimum feedrate forfine lEFAULT_REIGHTPAULFEEGATE 0.0	#define lEFAULT_HINEHEMPFENDATE 0.0 // minimum feedbate #define lEFAULT_HINEHEMPENDATE 0.0
// minimum time in microseconds that a movement meeds to take if the Doffer is emptied. Increase this mumb define lifeTutt_NIMECONINTINE 20100 // Obrobies delute this	// minimum time in microsecond; that a normannt needs to take if the huffer is captied. Increase this numb factors STANIT_MINIMUMTINE 2008 // Unselets delets this *	// minimum time in microseconds that a movement means to take if the buffer is emptied. Increase this makes the interval of the second of the
Compiling sketch.	Uploading.	Done uploating
	Binary shetch size: 53539 bytes (of a 120376 byte measure)	Binney sheath size: 51039 bytes (of a 114976 byte swalawa)
Article Maga (ATragat200) is CDM4	217 Antoine Meas (RT meas 1201) on COMP	217 Antonio Magar(ATrivaga1280) in COM4

Now you are ready to get started and set it up for printing. Grab the User Manual to get started!



3 APPENDIX: SYMBOL- AND INDICATORLIGHTS EXPLANATION

Symbol/indicator	Explanation
	Warning: High temperatures
	Pinch hazard.
Foto temperatuurlampje	Temperature indicator. When LED is on, temperature of



14 APPENDIX: TERMS OF SERVICE

Please read the entire agreement, you can always contact us if you have any questions. By using and ordering from our website you agree to these terms. If you do not agree, please do not use this product. If you have any questions or concerns, feel free to contact us. Thanks for your patience!

If you have any questions, please contact us.

- Liability
- Payment Terms
- Shipping & Processing Terms
- Accuracy of Information
- Validity of offers
- Privacy
- Revisions to these terms of service
- Termination
- Returns and warranty
- Copyright
- Trademarks
- Typographical Errors
- Miscellaneous
- Use of Site
- Participation Disclaimer
- Indemnification
- Third-Party Links

Liability

"FELIXrobotics" sees it as a duty to deliver you valuable products at reasonable prices. However, all of the products and services we offer are experimental and intended for the "maker" community. These products are not tested by independent laboratories like and should only be used by people who understand the risks. The products offered can be used to make machines of which nor the performance nor proper or safe operation can be guaranteed, as they are the sole responsibility of the experimenter that applies these products in their projects. We strive to contribute to assembly instructions, which the user may, or may not decide to follow. Assembly instructions are only partly provided by us and may include contributions made third parties. We cannot take responsibility for the safe nor proper execution of these assembly steps, nor do we accept responsibility of the functioning of the resulting assembly. FELIXrobotics strives to contribute to the documentation to support those who are using our products and kits.

Payment Terms

We accept credit card, PayPal and Dutch Wire Transfers as payment for orders. For Wire Transfers payments, the order will not ship until the payment is received and 'clears'. For PayPal eCheck, we will not ship until the payment clears. Due to potential fraud and misuse, we may decide not to ship an order, or request additional verification information for credit card or PayPal payments. Credit cards must clear the authorization process.

Shipping & Processing Terms

We can't add or remove any item to an order that has already been placed. Orders won't be combined, before or after they're placed; please put all your items in one order. Please check your shopping cart carefully before checking out and paying.

We strive to ship orders as soon as possible, however we do not guarantee specific delivery or shipment dates. Each order takes a minimum of one day. Orders are shipped to the delivery address noted in the customer order. This address is noted in the email sent to the customer upon ordering and is also available in the account order history. For international orders, you are also responsible for any tariffs, taxes, fees, VAT, duties due upon receipt.You are responsible for filing any claims with carriers for damaged and/or lost shipments. A customer may expect that we ship items that were in stock at the moment of purchase to be shipping within 30 days, unless these items are bought as part of a pre-order or are bundled with a pre-ordered item. In the exceptional case that items cannot be shipped in this period, we will contact you beforehand to try to arrive at an agreement on how to process, including the option to cancel the order. In case we send out a substitute product instead of the originally ordered product, we will pay for the costs of returning that product when requested. Such a request has to be sent to us within 14 days, and the product has to be in an undamaged and unused state, and we should be consulted for the courier service that is selected for the return.

We strongly encourage using a traceable shipping method. Use of non-traceable shipping is at customer's own risk and there is no way to retrieve or locate the package once it has been sent. We are not responsible for delays, loss or damage stemming from shipments sent to incorrect, invalid addresses or correct addresses. Orders may end up being returned for various reasons including: non-payment of tariffs, incorrect address, unclaimed at post office, etc. If a package is returned or rejected, the customer will be contacted and will have to pay for re-shipment postage. We are not responsible for damaged or lost packages shipped via untracked parcel services at any time and under any



circumstance.

Not all packages are insured. For DHL, packages are insured and claims may be filed almost immediately, but its best to wait a few days. For other parcel services that are un-tracked, no insurance is offered. Claims for lost or damaged packages must be filed no earlier than 21 days after shipment and before 90 days. For international packages, claims must be filed between 45-90 days except for Italy which is 60-90 days

Accuracy of Information

We attempt to ensure that all the information included on this Web Site is complete, accurate and current. Despite our efforts, the information on this Web Site may occasionally be inaccurate, incomplete or out of date. We make no representation as to the completeness, accuracy or correctness of any information on this Web Site. For example, products included on this Web Site may be unavailable, may have different attributes than those listed, or may actually carry a different price than that stated on this Web Site. In addition, we may make changes in information about price and availability without notice. While it is our practice to confirm orders by e-mail, the receipt of an e-mail order confirmation does not constitute our acceptance of an order or our confirmation of an offer to sell a product or service. We reserve the right, without prior notice, to limit the order quantity on any product or service and/or to refuse service to any customer. We also may require verification of information prior to the acceptance and/or shipment of any order. **Validity of offers**

Unless stated otherwise, offers are valid for up to 14 days.

Privacy

We store your phone number, order history, email, shipping and billing addresses in your user account. For your security, credit card numbers, expiration dates, and CVV codes are not stored. User information is only used to ship goods and contact you in case of an order or shipping issue. We do not, and will never sell or give any of your information to any third-party or send you any unsolicited advertisements. NEVER!

Revisions to these terms of service

These terms of service may be revised at any time and from time to time by updating this posting. You should visit this page from time to time to review the then current terms of service because they are binding on you. Certain provisions of these terms of service may be superseded by legal notices or terms located on particular pages of this Web Site. **Termination**

You or we may suspend or terminate your account or your use of this Web Site at any time, for any reason or for no reason. You are personally liable for any orders placed or charges incurred through your account prior to termination. We reserve the right to change, suspend, or discontinue all or any aspect of this Web Site at any time without notice. **Returns and warranty**

A customer may return a tangible product within at least 7 days, as long as it is unused, unopened and in the same condition as received. When you want to return a product, please contact us for details or see the last paragraph of this page for our address.

Defective products manufactured in house will be replaced within 10 days of receipt, with the same item. All goods are checked before they are sent out. In the unlikely event that goods are faulty, they must be returned, to the FELIXrobotics store at the address listed on your order invoice. FELIXrobotics will not accept goods that have clearly been used more than the amount needed to evaluate their functionality. If the goods are found to be in working condition, and the lack of functionality is a result of lack of knowledge or assembly error on the customers part, no refund will be made, but the goods will be returned to the user at their expense If there is evidence that the product has been modified or that a fix has been done on it, the FELIXrobotics store will not be made responsible and therefore will not provide an exchange. For other products distributed but not manufactured directly by the FELIXrobotics (i.e. Arduino's, Stepper motors, etc), we will ship a replacement item for the defective part within 14 days of delivery confirmation. The item must be as it was shipped, with no modifications, original packaging and contents. Order cancelations/refunds apply with the following conditions: 1. - When we cannot longer provide one or more items of the actual order (i.e. discontinued parts). 2. - When one or more items of the actual order are not expected to be shipped within 30 days or more. 3. - When one or more items of the actual order is marked as In Stock but was actually Out of Stock. Return shipment is the responsibility of the customer. All returns are credited as store credit upon receipt. RMAs are required for returns.

Copyright

The entire content included in this site, including but not limited to text, graphics or code is copyrighted as a collective work under the Netherlands and other copyright laws, and is the property of FELIXrobotics. The collective work includes works that are licensed to FELIXrobotics. Copyright 2011, FELIXrobotics, ALL RIGHTS RESERVED. (Terms of Service template courtesy of Adafruit Industries and DIY Drones.) Permission is granted to electronically copy and print hard copy portions of this site for the sole purpose of placing an order with FELIXrobotics or purchasing FELIXrobotics products. You may display and, subject to any expressly stated restrictions or limitations relating to specific material, download or print portions of the material from the different areas of the site solely for your own non-commercial use, or to place an order with FELIXrobotics or to purchase FELIXrobotics products. Any other use, including but not limited to the reproduction, distribution, display or transmission of the content of this site is strictly prohibited, unless authorized by FELIXrobotics. You further agree not to change or delete any proprietary notices from materials downloaded from the site.

Trademarks

All trademarks, service marks and trade names belong to their respective owners.



Typographical Errors

In the event that a FELIXrobotics product is mistakenly listed at an incorrect price, FELIXrobotics reserves the right to refuse or cancel any orders placed for product listed at the incorrect price. FELIXrobotics reserves the right to refuse or cancel any such orders whether or not the order has been confirmed and your credit card charged. If your credit card has already been charged for the purchase and your order is cancelled, FELIXrobotics shall issue a credit to your credit card account in the amount of the incorrect price.

Miscellaneous

Your use of this site shall be governed in all respects by Dutch law, without regard to choice of law provisions, and not by the 1980 U.N. Convention on contracts for the international sale of goods. You agree that jurisdiction over and venue in any legal proceeding directly or indirectly arising out of or relating to this site (including but not limited to the purchase of FELIXrobotics products) shall be in a Dutch court. Any cause of action or claim you may have with respect to the site (including but not limited to the purchase of FELIXrobotics products) must be commenced within one (1) year after the claim or cause of action arises. FELIXrobotics's failure to insist upon or enforce strict performance of any provision of these terms and conditions shall not be construed as a waiver of any provision or right. Neither the course of conduct between the parties nor trade practice shall act to modify any of these terms and conditions. FELIXrobotics may assign its rights and duties under this Agreement to any party at any time without notice to you.

Use of Site

Harassment in any manner or form on the site, including via e-mail, chat, or by use of obscene or abusive language, is strictly forbidden. Impersonation of others, including a FELIXrobotics or other licensed employee, host, or representative, as well as other members or visitors on the site is prohibited. You may not upload to, distribute, or otherwise publish through the site any content which is libelous, defamatory, obscene, threatening, invasive of privacy or publicity rights, abusive, illegal, or otherwise objectionable which may constitute or encourage a criminal offense, violate the rights of any party or which may otherwise give rise to liability or violate any law. You may not upload commercial content on the site or use the site to solicit others to join or become members of any other commercial online service or other organization.

Participation Disclaimer

FELIXrobotics does not and cannot review all communications and materials posted to or created by users accessing the site, and is not in any manner responsible for the content of these communications and materials. You acknowledge that by providing you with the ability to view and distribute user-generated content on the site, FELIXrobotics is merely acting as a passive conduit for such distribution and is not undertaking any obligation or liability relating to any contents or activities on the site. However, FELIXrobotics reserves the right to block or remove communications or materials that it determines to be (a) abusive, defamatory, or obscene, (b) fraudulent, deceptive, or misleading, (c) in violation of a copyright, trademark or; other intellectual property right of another or (d) offensive or otherwise unacceptable to FELIXrobotics in its sole discretion.

Indemnification

You agree to indemnify, defend, and hold harmless FELIXrobotics, its officers, directors, employees, agents, licensors and suppliers (collectively the "Service Providers") from and against all losses, expenses, damages and costs, including reasonable attorneys' fees, resulting from any violation of these terms and conditions or any activity related to your account (including negligent or wrongful conduct) by you or any other person accessing the site using your Internet account.

Third-Party Links

In an attempt to provide increased value to our visitors, FELIXrobotics may link to sites operated by third parties. However, even if the third party is affiliated with FELIXrobotics, FELIXrobotics has no control over these linked sites, all of which have separate privacy and data collection practices, independent of FELIXrobotics. These linked sites are only for your convenience and therefore you access them at your own risk. Nonetheless, FELIXrobotics seeks to protect the integrity of its web site and the links placed upon it and therefore requests any feedback on not only its own site, but for sites it links to as well (including if a specific link does not work).

Please Note - Before you begin any electronics project...

Technology, the laws, and limitations imposed by manufacturers and content owners are constantly changing. Thus, some of the projects described may not work, may be inconsistent with current laws or user agreements, or may damage or adversely affect some equipment.

Your safety is your own responsibility, including proper use of equipment and safety gear, and determining whether you have adequate skill and experience. Power tools, electricity, and other resources used for these projects are dangerous, unless used properly and with adequate precautions, including safety gear. Some illustrative photos do not depict safety precautions or equipment, in order to show the project steps more clearly. These projects are not intended for use by children.

Use of the instructions, kits, projects and suggestions on www.FELIXprinters.com is at your own risk. FELIXrobotics, disclaims all responsibility for any resulting damage, injury, or expense. It is your responsibility to make sure that your activities comply with applicable laws, including copyright.

Always check the webpage associated with each project before you get started. There may be important updates or corrections!

The United States Fire Administration (USFA) has a guide and many simple steps you can take to prevent the loss of life and property resulting from electrical fires. Click here to read them!



You can contact us by e-mail at: support@FELIXprinters.com. You are kindly asked to contact us before returning an item, for the following reasons:

- We may be able to provide revised instructions on how to use the product or circumvent the problem you may be having
- You may not need to send it back to us, sending us a photo of the defective item might be enough

So we can select a logistics partner of our choice that will handle the package. In this case we can choose to pay for shipping the return